

### **Vehicle Specifications**

| Hull dimension (L $\times$ W $\times$ H) | 1035mm*560mm*345mm              |
|--|---------------------------------|
| Material                                 | Carbon fiber, Rubber Bumper     |
| Anti-wave & Wind                         | 3rd wind level & 2nd wave level |
| Waterproof                               | IP67                            |
| Indicator light                          | Two-color light                 |
| Camera                                   | 360° omnidirectional video      |
| Anticollision sensor                     | Detection distance 5-30 meters  |
| Propeller type                           | Brushless DC                    |
| Direction control                        | Veering without steering engine |
| Maximum speed                            | 6m/s                            |
| Battery endurance                        | 10 hours@1.5m/s(two batteries)  |

### Controller

| System             | Android 7.0, storage 5GB; SD Card supported  |
|--------------------|--|
| Software           | SLHydro USV, an Android software for bathymetric surveys   |
| Display            | 7 inches   |
| Waterproof         | IP67   |
| R/C communication  | 2.4 GHz  |
| Transmission range | Bridge Mode: 1.3 km (RF point-to-point in real-time) 4G Mode: Unlimited Distance (4G network transmission) |
| Navigation mode    | Manual or Auto-Pilot   |

## **GNSS Performance**

| Satellite system |
|------------------|
| Channel          |

Single point position(RMS) ±0.5m + 1 p

DGNSS positioning accuracy
RTK Positioning accuracy

Heading accuracy

Data formats

Headquarters:

Regional Offices: Warsaw, Poland Jičín, Czech Republic Ankara, Turkey Scottsdale, USA Singapore Hong Kong, China Dubai, UAE

Järnbrotts Prästväg, 2 421 47 Vastra Frolunda Goteborg, Sweden info@satlab.com.se

www.satlab.com.se

### BDS B1/B2/B3, GPS L1/L2/L5, GLONASS L1/L2, Galileo E1/E5

432

±0.5m + 1 ppm ±0.25m + 1 ppm

0.2° @1 m baseline

RTCM V3.0/3.2 input NMEA 0183 output NTRIP, TCP/IP

### Single Beam Echo Sounder

| Depth range          | 0.15m - 200m  |
|----------------------|---|
| Accuracy             | ±0.01m + 0.1% x D (D is the depth of water)   |
| Frequency            | 200 kHz   |
| Beam angle           | 5±0.5°  |
| Software SLHydro USV | Project management: support project creation, application etc.  |
|                      | Coordinate system: built-in coordinate system worldwide, support coordinate transformation and grid                                       |
|                      | Mission planning: planning waypoints/lines, setting boat speed etc.   |
|                      | Auto-pilot: auto course and auto return   |
|                      | Echogram: automatic tracking depth, echo real-time display  |
|                      | Data acquisition: real-time acquisition of positioning and bathymetry data  |
| SLHydro Sounder      | Data post-processing software. Support import SLHydro USV project, analog signal superimposed digital bathymetry, feature point sampling, |



# HydroBoat 990

An Android-powered USV system for bathymetric surveys







data correction, and output various of data formats

# HydroBoat 990

USVs (Unmanned Surface Vehicles) are widely used in hydrographic surveys, environmental monitoring, and water search and rescue. Among them, hydrographic surveying is the most used and developed field. When a hydrological survey is facing many unknown waters, it usually takes a long time navigation and requires high accuracy, which poses great challenges to the safety and health of surveyors.

The hydrographic survey USV combines various complex systems to offer users the simple and efficient operation mode. With double hull design, HydroBoat 990 USV integrates the GNSS system, bathymetry system, communication system and autonomous navigation system, which ensures both efficient surveying and safe navigation.

# Top 3 Challenges about USV





# **Usability**

It is complicated and a waste of time repeating the unnecessary operational processes in many instances.





# **Functionality**

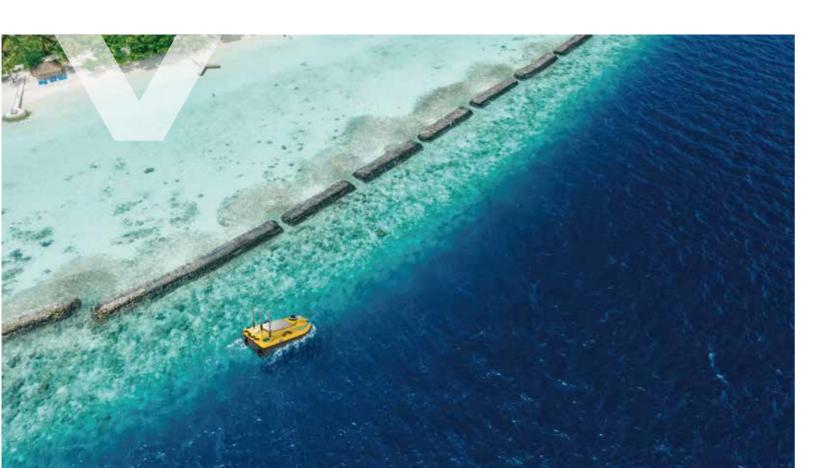
It is applicable to various environments with abundant functions which makes the surveying more convenient.





# Reliability

It is important to avoid USV from sinking and wrecking. Besides, every part should be maintained in good quality for such a complex system.



### -HydroBoat 990 bathymetric USV system

#### System of efficiency and reliability



Supported by auto and manual mode in the pilot system, safeguarded by radar's obstacle avoidance and hovering system.

Stable hull design for standing waves, IP67 waterproof, and rugged body with collision protection.

One-click connection with a powerful controller makes the USV a direct-to-go system, operating at ranges of 2km.

The pioneering Android app for hydrography and pilot control, makes surveying easier and faster with one intelligent controller.



#### Usability

- Operate in One Versatile app
- Time-saving Turn on and Survey
- Network without Base Station
- Integration with GNSS and SBES
- Connection with Indicator Lights



#### **Functionality**

- Stable Hovering Function
- Avoid Collision with Obstacles
- Real-time Video Patrol
- 4G Remote Control
- Auto-reverse in the Shallows



#### Reliability

- IP67 Double Hull
- Anti-Collision & Wear-Resisting
- IHO Standard & CE Certification
- Automotive Grade INS Integration
- Onboard Water Depth Logging